# Symbolic Evaluation Graphs and Term Rewriting — A General Methodology for Analyzing Logic Programs

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joint work with T. Ströder, P. Schneider-Kamp, F. Emmes, and C. Fuhs

## Termination Analysis for TRSs

$$egin{array}{rcl} \mathcal{R}: & {\sf double}(0) & 
ightarrow & 0 \ & {\sf double}({\sf s}(x)) & 
ightarrow & {\sf s}({\sf s}({\sf double}(x))) \end{array}$$

 $\mathcal R$  is *terminating* iff there is no infinite evaluation  $t_1 o_{\mathcal R} t_2 o_{\mathcal R} \dots$ 

 $\begin{array}{lll} \mbox{Computation of "double(1)":} & \mbox{double}(s(0)) & \rightarrow_{\mathcal{R}} s(s(\mbox{double}(0))) \\ & \rightarrow_{\mathcal{R}} s(s(0)) \end{array}$ 

- easier / more general than for programs
- suitable for automation
- But: halting problem is undecidable!
   ⇒ automated termination proofs do not always succeed

## Automated Termination Tools for TRSs

- AProVE (Aachen)
- CARIBOO (Nancy)
- CiME (Orsay)
- Jambox (Amsterdam)
- Matchbox (Leipzig)
- MU-TERM (Valencia)
- MultumNonMulta (Kassel)
- TEPARLA (Eindhoven)
- Termptation (Barcelona)
- TORPA (Eindhoven)
- TPA (Eindhoven)
- TTT (Innsbruck)
- VMTL (Vienna)

- Annual International Competition of Termination Tools
- well-developed field
- active research
- powerful techniques & tools
- But: What about application in practice?

#### **Functional Languages**

- first-order languages with strict evaluation strategy (Walther, 94), (Giesl, 95), (Lee, Jones, Ben-Amram, 01)
- ensuring termination (e.g., by typing) (Telford & Turner, 00), (Xi, 02), (Abel, 04), (Barthe et al, 04) etc.
- outermost termination of untyped first-order rewriting (Fissore, Gnaedig, Kirchner, 02), (Endrullis & Hendriks, 09), (Raffelsieper & Zantema, 09), (Thiemann, 09)
- automated technique for small HASKELL-like language (*Panitz & Schmidt-Schauss, 97*)
- do not work on full existing languages
- no use of TRS-techniques (stand-alone methods)

#### **Functional Languages**

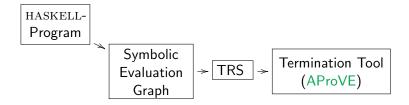
- using TRS-techniques for **HASKELL** is challenging
  - HASKELL has a lazy evaluation strategy. For TRSs, one proves termination of *all* reductions.
  - HASKELL's equations are handled from top to bottom. For TRSs, *any* rule may be used for rewriting.
  - HASKELL has polymorphic types. TRSs are *untyped*.
  - In HASKELL-programs, often only some functions terminate. TRS-methods try to prove termination of *all* terms.
  - HASKELL is a higher-order language. Most automatic TRS-methods only handle *first-order* rewriting.

#### **Functional Languages**

- using TRS-techniques for **HASKELL** is challenging
- New approach (ACM TOPLAS '11)
  - Frontend
    - evaluate HASKELL a few steps ⇒ symbolic evaluation graph graph captures evaluation strategy, types, etc.
    - transform symbolic evaluation graph  $\Rightarrow$  TRS
  - Backend
    - prove termination of the resulting TRS (using existing techniques & tools)
- implemented in AProVE
  - accepts full HASKELL 98 language
  - successfully evaluated with standard HASKELL-libraries (succeeds on approx. 80 % of the functions in standard libraries)

#### **Functional Languages**

• using TRS-techniques for **HASKELL** is challenging



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#### Imperative Languages

- Synthesis of Linear Ranking Functions (Colon & Sipma, 01), (Podelski & Rybalchenko, 04)
- Terminator: Termination Analysis by Abstraction & Model Checking (Cook, Podelski, Rybalchenko et al., since 05)
- Julia & COSTA: Termination Analysis of JAVA BYTECODE (Spoto, Mesnard, Payet, 10), (Albert, Arenas, Codish, Genaim, Puebla, Zanardini, 08)

• . . .

- used at Microsoft for verifying Windows device drivers
- no use of TRS-techniques (stand-alone methods)

## Imperative Languages

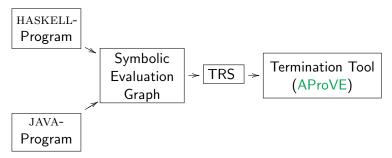
- using TRS-techniques for JAVA is challenging
  - sharing and aliasing
  - side effects
  - cyclic data objects
  - object-orientation
  - recursion
  - . . .

#### Imperative Languages

- using TRS-techniques for JAVA is challenging
- New approach (RTA '10, RTA '11, CAV '12)
  - Frontend
    - evaluate JAVA a few steps ⇒ symbolic evaluation graph graph captures side effects, sharing, cyclic data objects, etc.
    - transform symbolic evaluation graph  $\Rightarrow$  TRS
  - Backend
    - prove termination of the resulting TRS (using existing techniques & tools)
- implemented in **AProVE** 
  - successfully evaluated on JAVA-collection
  - most powerful termination tool for JAVA (winner of the international termination competition for JAVA)

#### Imperative Languages

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## Logic Languages

- well-developed field (De Schreye & Decorte, 94) etc.
- direct approaches: work directly on the logic program
  - cTI (Mesnard et al)
  - TerminWeb (Codish et al)
  - TermiLog (Lindenstrauss et al)
  - Polytool (Nguyen, De Schreye, Giesl, Schneider-Kamp)

TRS-techniques can be adapted to work *directly* on the LP

• transformational approaches: transform LP to TRS

 $\begin{array}{l} \operatorname{app}([], YS, YS).\\ \operatorname{app}([X \mid XS], YS, [X \mid ZS]) := \operatorname{app}(XS, YS, ZS).\\ \operatorname{app}^{in}([X \mid XS], YS) \to \operatorname{u}(\operatorname{app}^{in}(XS, YS), X)\\ \operatorname{u}(\operatorname{app}^{out}(ZS), X) \to \operatorname{app}^{out}([X \mid ZS]) \end{array}$ 

- class of queries  $Q_m^p$  described by predicate p and moding m Example:  $Q_m^{app} = \{app(t_1, t_2, t_3) | t_1, t_2 \text{ are ground}\}.$
- encode atom  $p(\ldots)$  to terms  $p^{in}(\ldots)$ ,  $p^{out}(\ldots)$ 
  - arguments of  $p^{in}$ : input arguments of  $p(\ldots)$
  - arguments of  $p^{out}$ : remaining arguments of  $p(\ldots)$

Encoding of app([], YS, YS): $app^{in}([], YS)$ ,  $app^{out}(YS)$ Encoding of app([X | XS], YS, [X | ZS]): $app^{in}([X | XS], YS)$ ,  $app^{out}([X | ZS])$ Encoding of app(XS, YS, ZS): $app^{in}(XS, YS)$ ,  $app^{out}(ZS)$ 

• encode clauses to rewrite rules

• fact  $p(\ldots)$ :  $p^{in}(\ldots) \rightarrow p^{out}(\ldots)$ • rule  $p(\ldots)$ :  $-q(\ldots)$ :  $p^{in}(\ldots) \rightarrow u(q^{in}(\ldots))$  $u(q^{out}(\ldots)) \rightarrow p^{out}(\ldots)$ 

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TRS-techniques can be adapted to work *directly* on the LP

- transformational approaches: transform LP to TRS
  - TALP (Ohlebusch et al)
  - AProVE (Giesl et al)
- only for *definite* LP (without cut)
- not for real PROLOG

## Logic Languages

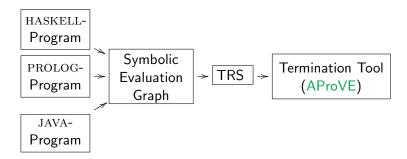
• analyzing **PROLOG** is challenging due to cuts etc.

#### • New approach

- Frontend
  - evaluate PROLOG a few steps ⇒ symbolic evaluation graph graph captures evaluation strategy due to cuts etc.
  - transform symbolic evaluation graph  $\Rightarrow$  TRS
- Backend
  - prove termination of the resulting TRS (using existing techniques & tools)
- implemented in AProVE
  - successfully evaluated on PROLOG-collections with cuts
  - most powerful termination tool for PROLOG (winner of termination competition for PROLOG)

## Logic Languages

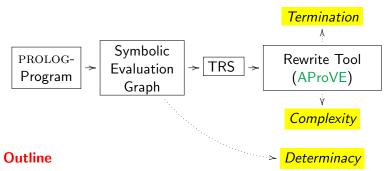
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## Symbolic Evaluation Graphs and Term Rewriting

#### General methodology for analyzing PROLOG programs



#### • linear operational semantics of PROLOG

- from PROLOG to symbolic evaluation graphs
- from symbolic evaluation graphs to TRSs for termination analysis
- from symbolic evaluation graphs to TRSs for complexity analysis
- determinacy analysis

$$\begin{array}{cccc} star(XS,[]) := !. & (1) \\ star([], ZS) := !, eq(ZS,[]). & (2) \\ star(XS, ZS) := app(XS, YS, ZS), star(XS, YS). & (3) \\ app([], YS, YS). & (4) \\ app([X | XS], YS, [X | ZS]) := app(XS, YS, ZS). & (5) \\ eq(X, X). & (6) \end{array}$$

• star( $t_1, t_2$ ) holds iff  $t_2$  results from concatenation of  $t_1$  ( $t_2 \in (t_1)^*$ )

- star([1, 2], []) holds
- star([1,2],[1,2]) holds, since app([1,2],[],[1,2]), star([1,2],[]) hold
- star([1,2], [1,2,1,2]) holds, etc.

cut in clause (2) needed for termination. Otherwise:
 star([], t) would lead to
 app([], YS, t), star([], YS) would lead to
 star([], t)

$$\begin{array}{cccc} star(XS,[]) := !. & (1) \\ star([], ZS) := !, eq(ZS,[]). & (2) \\ star(XS, ZS) := app(XS, YS, ZS), star(XS, YS). & (3) \\ app([], YS, YS). & (4) \\ app([X | XS], YS, [X | ZS]) := app(XS, YS, ZS). & (5) \\ eq(X, X). & (6) \end{array}$$

• state:  $(G_1 \mid \ldots \mid G_n)$  with current goal  $G_1$  and next goals  $G_2, \ldots, G_n$ 

# • goal: $(t_1, \ldots, t_k)$ query or $(t_1, \ldots, t_k)^c$ query labeled by clause c used for next resolution

#### • inference rules:

• CASE • EVAL • BACK • CUT • SUC • CASE  $star([1,2],[]) | = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(2)} | = star([1,2],[])^{(3)} | = EVAL$   $| = star([1,2],[])^{(3)} | = star([1,2],[])^{(3)} | = EVAL$  $| = star([1,2],[])^{(3)} | = star([1,2],[])$ 

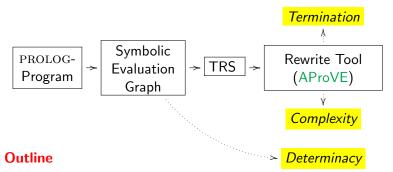
$$\begin{array}{cccc} {\rm star}(XS,[]):=!. & (1) \\ {\rm star}([],ZS):=!,{\rm eq}(ZS,[]). & (2) \\ {\rm star}(XS,ZS):={\rm app}(XS,YS,ZS),{\rm star}(XS,YS). & (3) \\ {\rm app}([],YS,YS). & (4) \\ {\rm app}([X\mid XS],YS,[X\mid ZS]):={\rm app}(XS,YS,ZS). & (5) \\ {\rm eq}(X,X). & (6) \end{array}$$

- state:  $(G_1 \mid \ldots \mid G_n)$  with current goal  $G_1$  and next goals  $G_2, \ldots, G_n$
- *linear* semantics, since state contains all backtracking information
   ⇒ evaluation is a sequence of states, not a search tree
- suitable for extension to abstract states

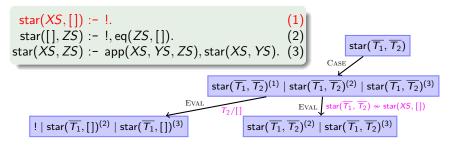
$$\begin{array}{ccc} \mathsf{star}([1,2],[]) & \vdash_{\mathrm{CASE}} \\ \mathsf{star}([1,2],[])^{(1)} \mid \mathsf{star}([1,2],[])^{(2)} \mid \mathsf{star}([1,2],[])^{(3)} & \vdash_{\mathrm{EVAL}} \\ & ! \mid \mathsf{star}([1,2],[])^{(2)} \mid \mathsf{star}([1,2],[])^{(3)} & \vdash_{\mathrm{CUT}} \\ & \Box & \vdash_{\mathrm{SUC}} \\ & \varepsilon \end{array}$$

## Symbolic Evaluation Graphs and Term Rewriting

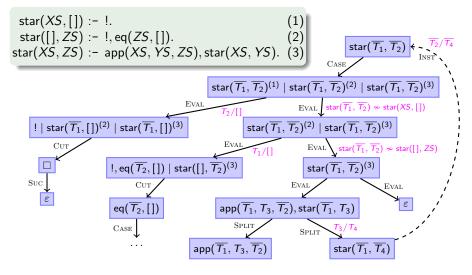
#### General methodology for analyzing PROLOG programs



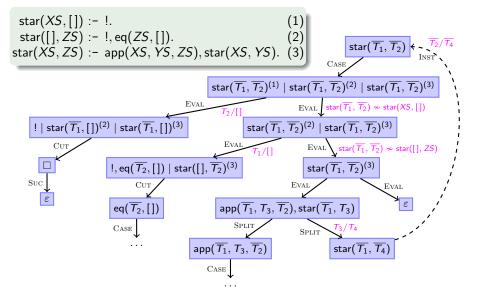
- linear operational semantics of PROLOG
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- symbolic evaluation graph: all evaluations for a class of queries
- class of queries  $Q_m^p$  described by predicate p and moding m Example:  $Q_m^{\text{star}} = \{ \text{star}(t_1, t_2) | t_1, t_2 \text{ are ground} \}.$
- abstract state: stands for set of concrete states
  - state with *abstract* variables  $T_1, T_2, \ldots$  representing arbitrary terms
  - constraints on the terms represented by  $T_1, T_2, \ldots$ 
    - groundness constraints:  $\overline{T_1}$ ,  $\overline{T_2}$
    - unification constraints:  $star(\overline{T_1}, \overline{T_2}) \approx star(XS, [])$

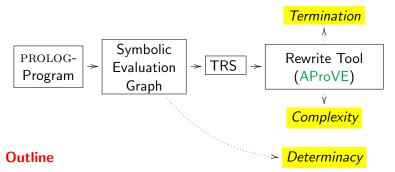


- INST: connection to previous state if current state is an *instance*
- $\bullet~\mathrm{SPLIT}:$  split away first atom from a query
  - $\bullet~$  fresh variables in  $\ensuremath{\operatorname{SPLIT}}$  's second successor
  - approximate first atom's answer substitution by groundness analysis

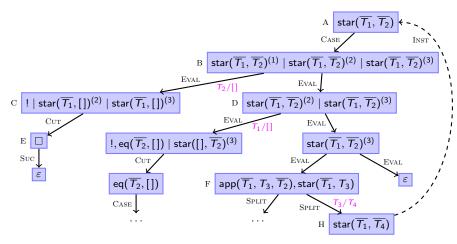


## Symbolic Evaluation Graphs and Term Rewriting

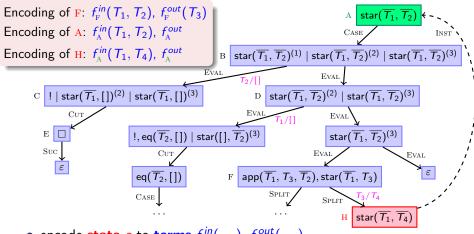
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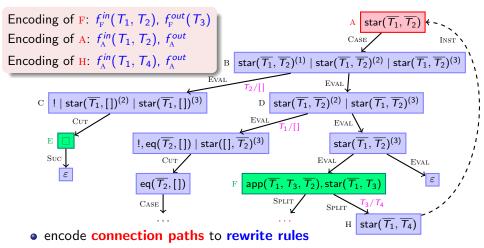


- Aim: show termination of concrete states represented by graph
- Solution: synthesize TRS from the graph
  - TRS captures all evaluations that are crucial for termination behavior
  - existing rewrite tools can show termination of TRS
    - $\Rightarrow$  prove termination of original  $\operatorname{PROLOG}$  program

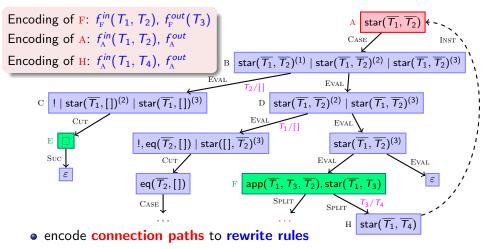


• encode state *s* to terms  $f_s^{in}(\ldots)$ ,  $f_s^{out}(\ldots)$ 

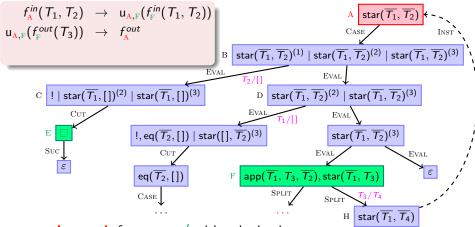
arguments of f<sup>in</sup><sub>s</sub>: abstract ground variables of s (T<sub>1</sub>, T<sub>2</sub>,...)
arguments of f<sup>out</sup><sub>s</sub>: remaining abstract variables of s which are made ground by every answer substitution of s (groundness analysis)
for state s with INST edge to s': use f<sup>in</sup><sub>s'</sub>, f<sup>out</sup><sub>s'</sub> instead of f<sup>in</sup><sub>s</sub>, f<sup>out</sup><sub>s</sub>



- connection path:
  - start state = root, successor of INST, or successor of SPLIT but no INST or SPLIT node itself
  - $\bullet~\mbox{end}$  state =  $\rm INST,~SPLIT,~SUC$  node, or successor of  $\rm INST$  node
  - $\bullet$  connection path may not traverse end nodes except  $\mathrm{Suc}$  nodes



- connection path: cover all ways through graph except
  - INST edges (are covered by the encoding of terms)
  - $\bullet~\mathrm{SPLIT}$  edges (will be covered by extra SPLIT rules later)
  - parts without cycles or SUC nodes (irrelevant for termination behavior)

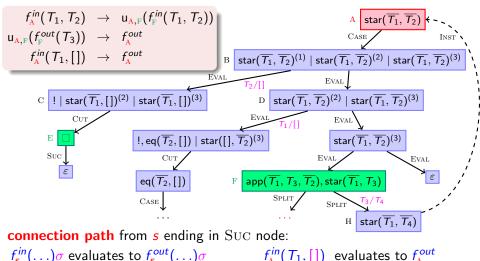


**connection path** from *s* to *s'* with substitution  $\sigma$ :

 $\begin{array}{ll} f_{s}^{in}(\ldots)\sigma \text{ evaluates to } f_{s}^{out}(\ldots)\sigma \text{ if } & f_{A}^{in}(T_{1},T_{2}) \text{ evaluates to } f_{A}^{out} \text{ if } \\ f_{s'}^{in}(\ldots) & \text{ evaluates to } f_{s'}^{out}(\ldots) & f_{F}^{in}(T_{1},T_{2}) \text{ evaluates to } f_{F}^{out}(T_{3}) \end{array}$ 

#### rewrite rules:

 $\begin{array}{ll} f_{\mathbf{s}}^{in}(\ldots)\sigma \rightarrow \mathsf{u}_{\mathbf{s},s'}(f_{s'}^{in}(\ldots)) & f_{\mathbf{A}}^{in}(T_1,T_2) \rightarrow \mathsf{u}_{A,F}(f_{F}^{in}(T_1,T_2)) \\ \mathsf{u}_{\mathbf{s},s'}(f_{s'}^{out}(\ldots)) \rightarrow f_{\mathbf{s}}^{out}(\ldots)\sigma & \mathsf{u}_{A,F}(f_{F}^{out}(T_3)) \rightarrow f_{A}^{out} \end{array}$ 

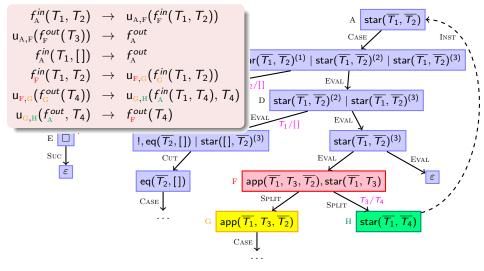


 $f_s^{in}(\ldots)\sigma$  evaluates to  $f_s^{out}(\ldots)\sigma$   $f_A^{in}(T_1,[])$ 

#### intuition:

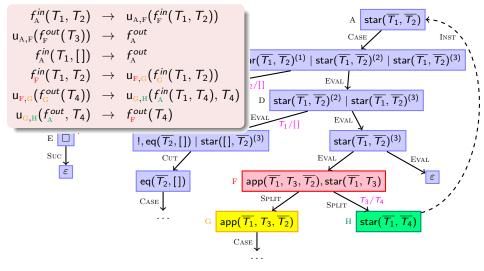
 $f_{A}^{in}(T_1, T_2)$  evaluates to  $f_{A}^{out}$  if  $T_2 \in (T_1)^*$ 

 $f_{\mathbb{F}}^{in}(T_1, T_2)$  evaluates to  $f_{\mathbb{F}}^{out}(T_3)$  if  $T_1 \neq [], T_2 \neq [], T_3$  is  $T_2$  without prefix  $T_1, T_3 \in (T_1)^*$ 



SPLIT node **s** with successors  $s_1$  and  $s_2$ :

 $f_{s}^{in}(\ldots)\sigma$  evaluates to  $f_{s}^{out}(\ldots)\sigma$  if  $f_{s_1}^{in}(\ldots)\sigma$  evaluates to  $f_{s_1}^{out}(\ldots)\sigma$  and  $f_{s_2}^{in}(\ldots)$  evaluates to  $f_{s_2}^{out}(\ldots)$   $f_{\rm F}^{in}(T_1, T_2)$  evaluates to  $f_{\rm F}^{out}(T_4)$  if  $f_{\rm G}^{in}(T_1, T_2)$  evaluates to  $f_{\rm G}^{out}(T_4)$  and  $f_{\rm A}^{in}(T_1, T_4)$  evaluates to  $f_{\rm A}^{out}$ 



#### intuition:

 $f_{F}^{in}(T_{1}, T_{2}) \text{ evaluates to } f_{F}^{out}(T_{4}) \quad \text{if } T_{1} \neq [], \ T_{2} \neq [], \ T_{4} \text{ is } T_{2} \text{ without prefix } T_{1}, \ T_{4} \in (T_{1})^{*}$   $f_{G}^{in}(T_{1}, T_{2}) \text{ evaluates to } f_{G}^{out}(T_{4}) \quad \text{if } T_{1} \neq [], \ T_{2} \neq [], \ T_{4} \text{ is } T_{2} \text{ without prefix } T_{1}$   $f_{A}^{in}(T_{1}, T_{4}) \text{ evaluates to } f_{A}^{out} \qquad \text{if } T_{4} \in (T_{1})^{*}$ 

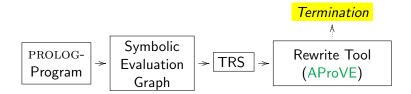
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$$\begin{array}{c} f_{\rm A}^{in}(T_1,T_2) \ \rightarrow \ {\sf u}_{{\rm A},{\rm F}}(f_{\rm F}^{in}(T_1,T_2)) \\ {\sf u}_{{\rm A},{\rm F}}(f_{\rm F}^{out}(T_3)) \ \rightarrow \ f_{\rm A}^{out} \\ f_{\rm A}^{in}(T_1,[]) \ \rightarrow \ f_{\rm A}^{out} \\ f_{\rm F}^{in}(T_1,T_2) \ \rightarrow \ {\sf u}_{{\rm F},{\rm G}}(f_{\rm G}^{in}(T_1,T_2)) \\ {\sf u}_{{\rm F},{\rm G}}(f_{\rm G}^{out}(T_4)) \ \rightarrow \ {\sf u}_{{\rm G},{\rm H}}(f_{\rm A}^{in}(T_1,T_4),T_4) \\ {\sf u}_{{\rm G},{\rm H}}(f_{\rm A}^{out},T_4) \ \rightarrow \ f_{\rm F}^{out}(T_4) \\ {\sf u}_{{\rm G},{\rm H}}(f_{\rm I}^{out}(T_3)) \ \rightarrow \ {\sf u}_{{\rm G},{\rm I}}(f_{\rm I}^{in}(T_6,T_7)) \\ {\sf u}_{{\rm G},{\rm I}}(f_{\rm I}^{out}(T_3)) \ \rightarrow \ f_{\rm G}^{out}(T_3) \\ {\sf i}^{in}([T_8 \mid T_9],[T_8 \mid T_{10}]) \ \rightarrow \ {\sf u}_{{\rm I},{\rm K}}(f_{\rm I}^{in}(T_9,T_{10})) \\ {\sf u}_{{\rm I},{\rm K}}(f_{\rm I}^{out}(T_3)) \ \rightarrow \ f_{\rm I}^{out}(T_3) \\ f_{\rm I}^{in}([],T_3) \ \rightarrow \ f_{\rm I}^{out}(T_3) \end{array}$$

f,

- existing TRS tools prove termination automatically
- original PROLOG program terminates

## Symbolic Evaluation Graphs and Term Rewriting

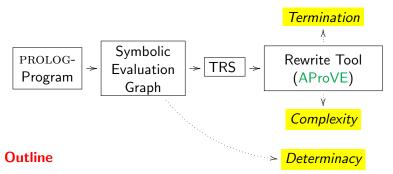


implemented in tool AProVE

- most powerful tool for termination of definite logic programs
- only tool for termination of non-definite PROLOG programs
- winner of *termination competition* for PROLOG (proves 342 of 477 examples, average runtime 6.5 s per example)

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- determinacy analysis

## Complexity for TRSs

$$egin{array}{ccc} \mathcal{R}: & \mathsf{double}(0) & o & \mathsf{0} \ & \mathsf{double}(\mathsf{s}(x)) & o & \mathsf{s}(\mathsf{s}(\mathsf{double}(x))) \end{array}$$

- *irc<sub>R</sub>* maps n ∈ N to maximal evaluation starting with basic term t, where |t| ≤ n
- |t|: number of variables and function symbols in t

$$double(s^{k}(0)) \rightarrow_{\mathcal{R}}^{k+1} s^{2 \cdot k}(0)$$
$$double^{k}(s(0)) \rightarrow_{\mathcal{R}}^{2^{k}+k-1} s^{2^{k}}(0)$$

- only consider **basic terms**  $f(t_1, \ldots, t_n)$ 
  - f defined symbol (double),  $t_1, \ldots, t_n$  no defined symbols (s, 0)

# Complexity for TRSs

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- |t|: number of variables and function symbols in t

double(s<sup>k</sup>(0)) 
$$\rightarrow_{\mathcal{R}}^{k+1}$$
 s<sup>2·k</sup>(0)

- $\mathcal{R}$  has linear complexity if  $irc_{\mathcal{R}}(n) \in \mathcal{O}(n)$  $\mathcal{R}$  has quadratic complexity if  $irc_{\mathcal{R}}(n) \in \mathcal{O}(n^2)$  etc.
- Example: has linear complexity
- Recently: many powerful techniques for complexity of TRSs (by adapting techniques for termination analysis)

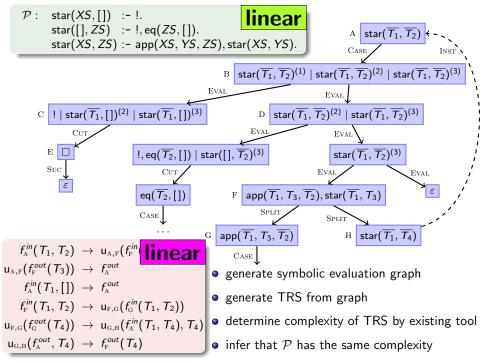
### Complexity for Logic Programs

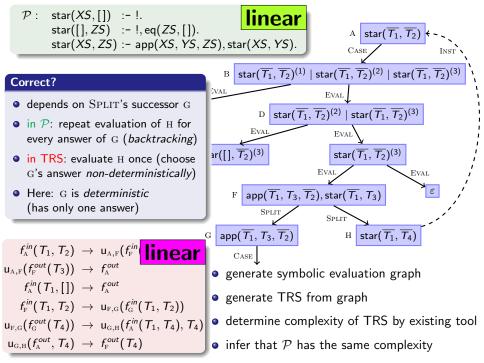
**Program**  $\mathcal{P}$ , **Class of queries**  $\mathcal{Q}_m^p$ 

•  $prc_{\mathcal{P},\mathcal{Q}_m^p}$  maps  $n \in \mathbb{N}$  to longest evaluation starting with  $Q \in \mathcal{Q}_m^p$ , where  $|Q|_m \leq n$ 

- $|Q|_m$ : number of variables and function symbols on *input positions*
- corresponds to number of unification attempts

- $\mathcal{P}$  has linear complexity for class  $\mathcal{Q}_m^p$  if  $prc_{\mathcal{P},\mathcal{Q}_m^p}(n) \in \mathcal{O}(n)$  $\mathcal{P}$  has quadratic complexity for class  $\mathcal{Q}_m^p$  if  $prc_{\mathcal{P},\mathcal{Q}_m^p}(n) \in \mathcal{O}(n^2)$  etc.
- Example (star-program): has linear complexity
- Goal: Re-use existing methodology for termination analysis to analyze complexity as well

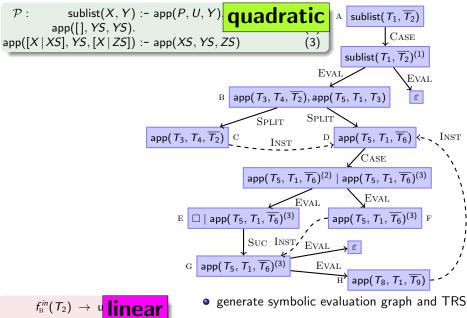




$$\mathcal{P}: \qquad \begin{array}{c} \text{sublist}(X,Y) := \operatorname{app}(P,U,Y) \\ \begin{array}{c} \text{quadratic} \\ \text{app}([],YS,YS). \\ \begin{array}{c} \text{app}([X|XS],YS,[X|ZS]) := \operatorname{app}(XS,YS,ZS) \end{array} \end{array}$$

#### Evaluation of sublist

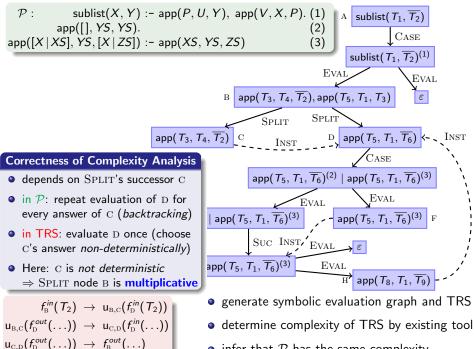
- $\mathcal{Q}_m^{\text{sublist}} = \{ \text{sublist}(t_1, t_2) | t_2 \text{ ground} \}$
- computes all sublists of Y (by backtracking)
- $\mathcal{P}$ : quadratic complexity
  - linear many possibilities to split Y into P and U
  - for each possible *P*, linear evaluation of app(*V*, *X*, *P*)



 $u_{B,C}(f_D^{out}(\ldots)) \rightarrow u_{C,D}(f_D^{m}(\ldots))$ 

 $u_{\text{C},\text{D}}(f_{\text{D}}^{out}(\ldots)) \rightarrow f_{\text{B}}^{out}(\ldots)$ 

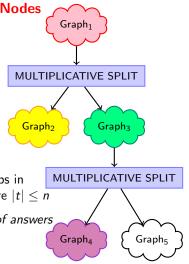
- determine complexity of TRS by existing tool
- infer that  $\mathcal{P}$  has the same complexity

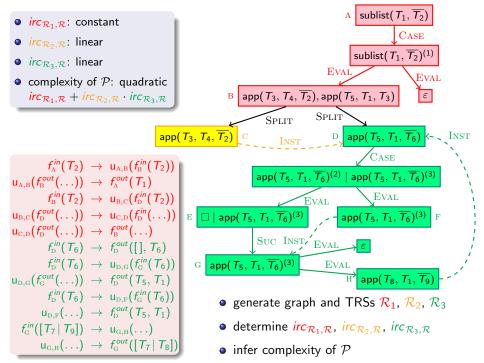


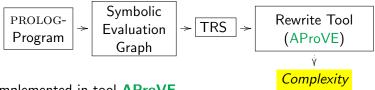
• infer that  $\mathcal{P}$  has the same complexity

#### Decompose Graph by Multiplicative Split Nodes

- generate symbolic evaluation graph
- generate separate TRSs R<sub>1</sub>,..., R<sub>5</sub> for parts up to multiplicative SPLIT nodes (no multiplicative SPLIT node may reach itself)
- determine  $irc_{\mathcal{R}_1,\mathcal{R}}, \ldots, irc_{\mathcal{R}_5,\mathcal{R}}$  separately
  - maps  $n \in \mathbb{N}$  to maximal number of  $\mathcal{R}_i$ -steps in evaluation starting with basic term t, where  $|t| \leq n$
  - upper bound for *runtime* and for *number of answers*
- combine complexities
  - multiply complexities for children of multiplicative SPLITs
  - add complexities of parents of multiplicative SPLITS
  - $irc_{\mathcal{R}_{1},\mathcal{R}} + irc_{\mathcal{R}_{2},\mathcal{R}} \cdot (irc_{\mathcal{R}_{3},\mathcal{R}} + irc_{\mathcal{R}_{4},\mathcal{R}} \cdot irc_{\mathcal{R}_{5},\mathcal{R}})$







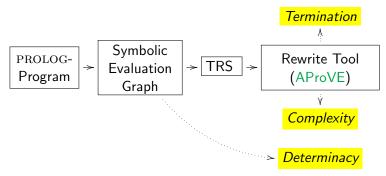
implemented in tool **AProVE** 

- only tool for complexity of non-well-moded or non-definite programs
- experiments on all 477 programs of TPDB

	$\mathcal{O}(1)$	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	$\mathcal{O}(n \cdot 2^n)$	bounds	time
CASLOG	1	21	4	3	29	14.8
CiaoPP	3	19	4	3	29	11.7
AProVE	54	117	37	0	208	10.6

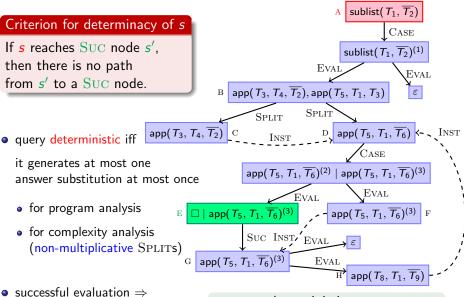
## Symbolic Evaluation Graphs and Term Rewriting

General methodology for analyzing PROLOG programs



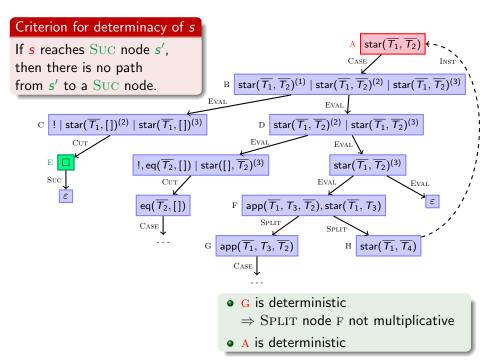
#### Outline

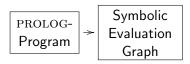
- linear operational semantics of PROLOG
- from PROLOG to symbolic evaluation graphs
- from symbolic evaluation graphs to TRSs for termination analysis
- from symbolic evaluation graphs to TRSs for complexity analysis
- determinacy analysis



path to  $\mathop{\rm Suc}\nolimits$  node in symbolic evaluation graph

- C not deterministic  $\Rightarrow$  SPLIT node B multiplicative
- A not deterministic





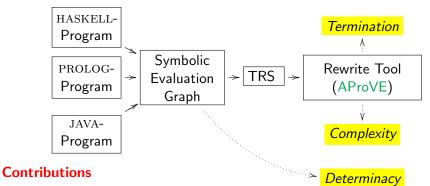
implemented in tool AProVE

• experiments on 300 definite programs: CiaoPP: 132, AProVE: 80

- experiments on 177 non-definite programs: CiaoPP: 61, AProVE: 92
- only first step, but substantial addition to existing determinacy analyses (AProVE succeeds on 78 examples where CiaoPP fails)
- strong enough for complexity analysis

# Symbolic Evaluation Graphs and Term Rewriting

#### General methodology for analyzing PROLOG programs



- linear operational semantics of PROLOG
- from PROLOG to symbolic evaluation graphs
- from symbolic evaluation graphs to TRSs for termination analysis
- from symbolic evaluation graphs to TRSs for complexity analysis
- determinacy analysis

#### http://aprove.informatik.rwth-aachen.de